Product data sheet Characteristics

ATV12H075F1

variable speed drive ATV12 - 0.75kW - 1hp - 100..120V - 1ph - with heat sink





Main

| Man | | |
|------------------------------------|--|---|
| Range of product | Altivar 12 | |
| Product or component type | Variable speed drive | |
| Product destination | Asynchronous motors | |
| Product specific application | Simple machine | |
| Assembly style | With heat sink | |
| Component name | ATV12 | |
| Quantity per set | Set of 1 | |
| EMC filter | Without EMC filter | |
| Built-in fan | With | |
| Network number of phases | 1 phase | |
| [Us] rated supply voltage | 100120 V - 1510 % | |
| Motor power kW | 0.75 kW | |
| Motor power hp | 1 hp | |
| Communication port protocol | Modbus | |
| Line current | 18.9 A 100 V 15.7 A 120 V | : |
| Speed range | 120 | |
| Transient overtorque | 150170 % of nominal motor torque depending on drive rating and type of motor | |
| Asynchronous motor control profile | Quadratic voltage/frequency ratio Sensorless flux vector control Voltage/Frequency ratio (V/f) | |
| IP degree of protection | IP20 without blanking plate on upper part | |
| Noise level | 45 dB | |
| | | |

Complementary

| o o p . o to y | | |
|--------------------|-----------------------------|---|
| Supply frequency | 50/60 Hz +/- 5 % | |
| Type of connector | 1 RJ45 Modbus on front face | Ę |
| Physical interface | 2-wire RS 485 Modbus | |

| Transmission frame | RTU Modbus | |
|-------------------------------------|--|--|
| Transmission rate | 4800 bit/s | |
| | 9600 bit/s 19200 bit/s | |
| | 38400 bit/s | |
| Number of addresses | 1247 Modbus | |
| Communication service | Read holding registers (03) 29 words | |
| | Write single register (06) 29 words Write multiple registers (16) 27 words | |
| | Read/Write multiple registers (23) 4/4 words | |
| | Read device identification (43) | |
| Prospective line Isc | <= 1 kA | |
| Continuous output current | 4.2 A 4 kHz | |
| Maximum transient current | 6.3 A 60 s | |
| Speed drive output frequency | 0.5400 Hz | |
| Nominal switching frequency | 4 kHz | |
| Switching frequency | 216 kHz adjustable 416 kHz with derating factor | |
| Braking torque | Up to 70 % of nominal motor torque without braking resistor | |
| Motor slip compensation | Adjustable Preset in factory | |
| Output voltage | 200240 V 3 phases | |
| Electrical connection | Terminal 5.5 mm² AWG 10 L1, L2, L3, U, V, W, PA, PC | |
| Tightening torque | 1.2 N.m | |
| Insulation | Electrical between power and control | |
| Supply | Internal supply for reference potentiometer 5 V DC 4.755.25 V 10 mA overload and short-circuit | |
| | protection Internal supply for logic inputs 24 V DC 20.428.8 V 100 mA overload and short-circuit protection | |
| Analogue input number | 1 | |
| Analogue input type | Configurable voltage Al1 010 V 30 kOhm Configurable voltage Al1 05 V 30 kOhm Configurable current Al1 020 mA 250 Ohm | |
| Discrete input number | 4 | |
| Discrete input type | Programmable LI1LI4 24 V 1830 V | |
| Discrete input logic | Negative logic (sink) > 16 V < 10 V 3.5 kOhm Positive logic (source) 0< 5 V > 11 V | |
| Sampling duration | < 20 ms +/- 1 ms logic input < 10 ms analogue input | |
| Linearity error | +/- 0.3 % of maximum value analogue input | |
| Analogue output number | 1 | |
| Analogue output type | Software-configurable voltage AO1 010 V 470 Ohm 8 bits Software-configurable current AO1 020 mA 800 Ohm 8 bits | |
| Discrete output number | 2 | |
| Discrete output type | Logic output LO+, LO- Protected relay output R1A, R1B, R1C 1 C/O | |
| Minimum switching current | 5 mA 24 V DC logic relay | |
| Maximum switching current | 2 A 250 V AC inductive cos phi = 0.4 L/R = 7 ms logic relay | |
| | 2 A 30 V DC inductive cos phi = 0.4 L/R = 7 ms logic relay 3 A 250 V AC resistive cos phi = 1 L/R = 0 ms logic relay 4 A 30 V DC resistive cos phi = 1 L/R = 0 ms logic relay | |
| Acceleration and deceleration ramps | Linear from 0 to 999.9 s | |
| Addictation and deceleration ramps | S U | |
| Braking to standstill | By DC injection 0.130 s | |
| Protection type | Against input phase loss in three-phase Thermal motor protection via the drive by continuous calculation of I²t Line supply overvoltage Line supply undervoltage Overcurrent between output phases and earth Overheating protection Short-circuit between motor phases | |

| Frequency resolution | 0.1 Hz display unit Converter A/D, 10 bits analog input | |
|--|---|--|
| Time constant | 20 ms +/- 1 ms for reference change | |
| Marking | CE | |
| Operating position | Vertical +/- 10 degree | |
| Height | 142 mm | |
| Width | 105 mm | |
| Depth | 156.2 mm | |
| Product weight | 1.3 kg | |
| Specific application | Commercial equipment | |
| Variable speed drive application selection | Commercial equipment : mixer Commercial equipment : other application Textile : ironing | |
| Motor power range AC-3 | 0.551 kW at 100120 V 1 phase | |
| Motor starter type | Variable speed drive | |

Environment

| Electromagnetic compatibility | Immunity to conducted disturbances level 3 EN/IEC 61000-4-6 Surge immunity test level 3 EN/IEC 61000-4-5 Voltage dips and interruptions immunity test EN/IEC 61000-4-11 Electrical fast transient/burst immunity test level 4 EN/IEC 61000-4-4 Electrostatic discharge immunity test level 3 EN/IEC 61000-4-2 Radiated radio-frequency electromagnetic field immunity test level 3 EN/IEC 61000-4-3 | |
|---------------------------------------|--|--|
| Electromagnetic emission | Radiated emissions environment 1 category C2 EN/IEC 61800-3 216 kHz shielded motor cable Conducted emissions with additional EMC filter environment 1 category C1 EN/IEC 61800-3 412 kHz shielded motor cable <= 5 m Conducted emissions with additional EMC filter environment 1 category C2 EN/IEC 61800-3 412 kHz shielded motor cable <= 20 m Conducted emissions with additional EMC filter environment 2 category C3 EN/IEC 61800-3 412 kHz shielded motor cable <= 20 m | |
| Product certifications | CSA C-Tick GOST NOM UL | |
| Vibration resistance | 1 gn EN/IEC 60068-2-6 13200 Hz 1.5 mm peak to peak EN/IEC 60068-2-6 313 Hz drive unmounted on symmetrical DIN rail | |
| Shock resistance | 15 gn EN/IEC 60068-2-27 11 ms | |
| Relative humidity | 595 % without condensation IEC 60068-2-3 595 % without dripping water IEC 60068-2-3 | |
| Ambient air temperature for storage | -2570 °C | |
| Ambient air temperature for operation | -1050 °C protective cover from the top of the drive removed 5060 °C with current derating 2.2 % per °C | |
| Operating altitude | > 10002000 m with current derating 1 % per 100 m <= 1000 m without derating | |
| | | |

Offer Sustainability

| Sustainable offer status | Green Premium product | |
|----------------------------------|---|--|
| RoHS (date code: YYWW) | Compliant - since 0901 - Schneider Electric declaration of conformity | |
| | Schneider Electric declaration of conformity | |
| REACh | Reference not containing SVHC above the threshold | |
| | Reference not containing SVHC above the threshold | |
| Product environmental profile | Available | |
| | End of life manual | |
| Product end of life instructions | Available | |
| | 🚰 End of life manual | |

Warranty period

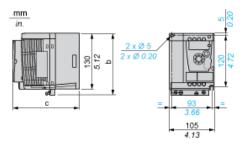
18 months

Product data sheet Dimensions Drawings

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Dimensions

Drive without EMC Conformity Kit



Dimensions in mm

| b | С |
|-----|-------|
| 142 | 156.2 |

Dimensions in in.

| b | С |
|------|------|
| 5.59 | 6.15 |

Drive with EMC Conformity Kit

Dimensions in mm

| b1 | |
|-------|--|
| 188.2 | |

Dimensions in in.

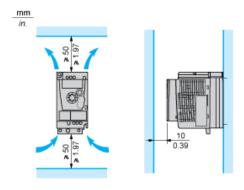
| b1 | | |
|------|--|--|
| 7.41 | | |

Product data sheet Mounting and Clearance

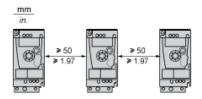
ATV12H075F1

Mounting Recommendations

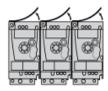
Clearance for Vertical Mounting



Mounting Type A

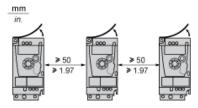


Mounting Type B



Remove the protective cover from the top of the drive.

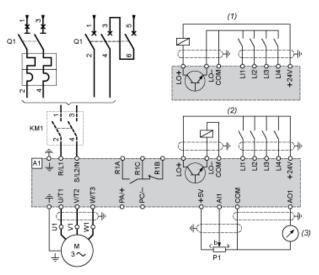
Mounting Type C



Remove the protective cover from the top of the drive.

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Single-Phase Power Supply Wiring Diagram



- A1 Drive
- KM1 Contactor (only if a control circuit is needed)
- P1 2.2 k Ω reference potentiometer. This can be replaced by a 10 k Ω potentiometer (maximum).
- Q1 Circuit breaker
- (1) Negative logic (Sink)
- (2) Positive logic (Source) (factory set configuration)
- (3) 0...10 V or 0...20 mA

Product data sheet Connections and Schema

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Recommended Schemes

2-Wire Control for Logic I/O with Internal Power Supply

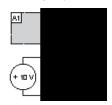
LI1: Forward LI•: Reverse A1: Drive

3-Wire Control for Logic I/O with Internal Power Supply



LI1: Stop LI2: Forward LI•: Reverse A1: Drive

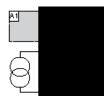
Analog Input Configured for Voltage with Internal Power Supply



(1) 2.2 $k\Omega$...10 $k\Omega$ reference potentiometer

A1: Drive

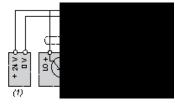
Analog Input Configured for Current with Internal Power Supply



(2) 0-20 mA 4-20 mA supply

A1: Drive

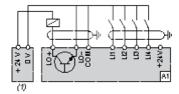
Connected as Positive Logic (Source) with External 24 vdc Supply



(1) 24 vdc supply

A1: Drive

Connected as Negative Logic (Sink) with External 24 vdc supply



(1) 24 vdc supply A1: Drive

Product data sheet Performance Curves

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Torque Curves

- 1: Self-cooled motor: continuous useful torque (1)
- 2: Force-cooled motor: continuous useful torque
- 3: Transient overtorque for 60 s
- 4: Transient overtorque for 2 s
- 5: Torque in overspeed at constant power (2)
- (1) For power ratings ≤ 250 W, derating is 20% instead of 50% at very low frequencies.
- (2) The nominal motor frequency and the maximum output frequency can be adjusted from 0.5 to 400 Hz. The mechanical overspeed capability of the selected